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[2] D.O. Hebb, Organization of Behaviour, Wiley, New York, 1949.

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# On Common Fixed Point and Approximation Results of Gregus Type

S. Al-Mezel and N. Hussain

Department of Mathematics King Abdul Aziz University P. O. Box 80203, Jeddah 21589, Saudi Arabia

#### Abstract

Fixed point theorems of Ciric [3], Fisher and Sessa [4], Gregus [5], Jungck [10] and Mukherjee and Verma [17] are generalized to a locally convex space. As applications, common fixed point and invariant approximation results for subcompatible maps are obtained. Our results unify and generalize various known results to a more general class of noncommuting mappings.

Mathematics Subject Classification: 47H10, 54H25

**Keywords:** Common fixed points, compatible maps, subcompatible maps, Minkowski functional, invariant approximation

#### 1. Introduction and preliminaries

In the sequel,  $(E, \tau)$  will be a Hausdorff locally convex topological vector space. A family  $\{p_{\alpha} : \alpha \in I\}$  of seminorms defined on E is said to be an associated family of seminorms for  $\tau$  if the family  $\{\gamma U : \gamma > 0\}$ , where  $U = \bigcap_{i=1}^n U_{\alpha_i}$  and  $U_{\alpha_i} = \{x : p_{\alpha_i}(x) < 1\}$ , froms a base of neighborhoods of zero for  $\tau$ . A family  $\{p_{\alpha} : \alpha \in I\}$  of seminorms defined on E is called an augmented associated family for  $\tau$  if  $\{p_{\alpha} : \alpha \in I\}$  is an associated family with property that the seminorm  $\max\{p_{\alpha}, p_{\beta}\} \in \{p_{\alpha} : \alpha \in I\}$  for any  $\alpha, \beta \in I$ . The associated and augmented associated families of seminorms will be denoted by  $A(\tau)$  and  $A^*(\tau)$ , respectively. It is well known that given a locally convex space  $(E, \tau)$ , there always exists a family  $\{p_{\alpha} : \alpha \in I\}$  of seminorms defined on E such that  $\{p_{\alpha} : \alpha \in I\} = A^*(\tau)$  (see[16, page 203]).

The following construction will be crucial. Suppose that M is  $\tau$ -bounded subset of E. For this set M we can select a number  $\lambda_{\alpha} > 0$  for each  $\alpha \in I$  such that  $M \subset \lambda_{\alpha}U_{\alpha}$  where  $U_{\alpha} = \{x : p_{\alpha}(x) \leq 1\}$ . Clearly  $B = \bigcap_{\alpha} \lambda_{\alpha}U_{\alpha}$  is  $\tau$ -bounded,  $\tau$ -closed absolutely convex and contains M. The linear span  $E_B$  of B in E is  $\bigcup_{n=1}^{\infty} nB$ . The Minkowski functional of B is a norm  $\|\cdot\|_B$  on  $E_B$ . Thus  $(E_B, \|\cdot\|_B)$  is a normed space with B as its closed unit ball and  $\sup_{\alpha} p_{\alpha}(x/\lambda_{\alpha}) = \|x\|_B$  for each  $x \in E_B$  (for details see [16,25]).

Let M be a subset of a locally convex space  $(E,\tau)$ . Let  $I:M\to M$ be a mapping. A mapping  $T: M \to M$  is called I-Lipschitz if there exists  $k \geq 0$  such that  $p_{\alpha}(Tx - Ty) \leq kp_{\alpha}(Ix - Iy)$  for any  $x, y \in M$  and for all  $p_{\alpha} \in A^*(\tau)$ . If k < 1 (respectively, k = 1), then T is called an I-contraction (respectively, I-nonexpansive). A point  $x \in M$  is a common fixed point of I and T if x = Ix = Tx. The set of fixed points of T is denoted by F(T). The pair  $\{I,T\}$  is called (1) commuting if TIx = ITx for all  $x \in M$ , (2) R-weakly commuting if for all  $x \in M$  and for all  $p_{\alpha} \in A^*(\tau)$ , there exists R > 0 such that  $p_{\alpha}(ITx - TIx) \leq Rp_{\alpha}(Ix - Tx)$ . If R = 1, then the maps are called weakly commuting [20]; (3) compatible [10,11,22] if for all  $p_{\alpha} \in A^*(\tau)$ ,  $\lim_n p_{\alpha}(TIx_n - TIx_n)$  $ITx_n$  = 0 whenever  $\{x_n\}$  is a sequence such that  $\lim_n Tx_n = \lim_n Ix_n = t$ for some t in M. Suppose that M is q-starshaped with  $q \in F(I)$  and is both T- and I-invariant. Then T and I are called (4) R-subcommuting on M (see [21]) if for all  $x \in M$  and for all  $p_{\alpha} \in A^*(\tau)$ , there exists a real number R > 0such that  $p_{\alpha}(ITx - TIx) \leq \frac{R}{k}p_{\alpha}(((1-k)q + kTx) - Ix)$  for each  $k \in (0,1)$ . If R = 1, then the maps are called 1-subcommuting [7]; (5) R-subweakly commuting on M (see [8,9]) if for all  $x \in M$  and for all  $p_{\alpha} \in A^*(\tau)$ , there exists a real number R>0 such that  $p_{\alpha}(ITx-TIx)\leq Rd_{p_{\alpha}}(Ix,[q,Tx])$ , where  $[q,x] = \{(1-k)q + kx : 0 \le k \le 1\}$ . It is well known that R-weakly commuting, R-subcommuting and R-subweakly commuting maps are compatible but not conversely in general (see [10-12]).

If  $u \in E, M \subseteq E$ , then we define the set  $P_M(u)$  of best M-approximants to u as  $P_M(u) = \{y \in M : p_\alpha(y-u) = d_{p_\alpha}(u,M), \text{ for all } p_\alpha \in A^*(\tau)\}$ , where  $d_{p_\alpha}(u,M) = \inf\{p_\alpha(x-u) : x \in M\}$ . A mapping  $T: M \to E$  is called demiclosed at 0 if whenever  $\{x_n\}$  converges weakly to x and  $\{Tx_n\}$  converges to 0, we have Tx = 0.

In [4], Fisher and Sessa obtained the following generalization of a theorem of Gregus [5].

**Theorem 1.1.** Let T and I be two weakly commuting mappings on a closed convex subset C of a Banach space X into itself satisfying the inequality,

 $||Tx - Ty|| \le a||Ix - Iy|| + (1 - a) \max\{||Tx - Ix||, ||Ty - Iy||\},$  (1.1) for all  $x, y \in C$ , where  $a \in (0, 1)$ . If I is linear and nonexpansive on C and  $T(C) \subseteq I(C)$ , then T and I have a unique common fixed point in C.

In 1988, Mukherjee and Verma [17] replaced linearity of I by affineness in Theorem 1.1. Subsequently, Jungck [12] obtained the following generalization of Theorem 1.1 and the result of Mukherjee and Verma [17].

**Theorem 1.2.** Let T and I be compatible self maps of a closed convex subset C of a Banach space X. Suppose that I is continuous, linear and that  $T(C) \subset I(C)$ . If T and I satisfy inequality (1.1), then T and I have a unique common fixed point in C.

In this paper, we first prove that Theorems 1.1-1.2 can appreciably be extended to the setup of Hausdorff locally convex space. As applications, common fixed point and invariant approximation results for a new class of subcompatible maps are derived. Our results extend and unify the work of Al-Thagafi [1], Ciric [3], Fisher and Sessa [4], Gregus [5], Habiniak [6], Hussain and Khan [7], Hussain et al. [8], Jungck [10], Jungck and Sessa [13], Khan and Hussain [14], Khan at el. [15], Mukherjee and Verma [17], Sahab, Khan and Sessa [18], Singh [23,24] and many others.

#### 2. Main Results

We begin with the definition of subcompatible mappings.

**Definition 2.1.** Let M be a q-starshaped subset of a normed space E. For the selfmaps I and T of M with  $q \in F(I)$ , we define  $S_q(I,T) := \cup \{S(I,T_k) : 0 \le k \le 1\}$  where  $T_k x = (1-k)q + kTx$  and  $S(I,T_k) = \{\{x_n\} \subset M : lim_n Ix_n = lim_n T_k x_n = t \in M \Rightarrow lim_n ||IT_k x_n - T_k Ix_n|| = 0\}$ . Now I and T are subcompatible if  $lim_n ||ITx_n - TIx_n|| = 0$  for all sequences  $\{x_n\} \in S_q(I,T)$ . We can extend this definition to locally convex space by replacing norm with a family of seminorms.

Clearly, subcompatible maps are compatible but the converse does not hold, in general, as the following example shows.

Example 2.2. Let X = R with usual norm and  $M = [1, \infty)$ . Let I(x) = 2x - 1 and  $T(x) = x^2$ , for all  $x \in M$ . Let q = 1. Then M is q-starshaped with Iq = q. Note that I and T are compatible. For any sequence  $\{x_n\}$  in M with  $\lim_n x_n = 2$ , we have,  $\lim_n Ix_n = \lim_n T_{\frac{2}{3}}x_n = 3 \in M, \Rightarrow \lim_n ||IT_{\frac{2}{3}}x_n - T_{\frac{2}{3}}Ix_n|| = 0$ . However,  $\lim_n ||ITx_n - TIx_n|| \neq 0$ . Thus I and T are not subcompatible

 $q \in F(I)$  and  $T(M) \subseteq I(M)$ . If the pair  $\{I, T\}$  is subcompatible and satisfies, for all  $p_{\alpha} \in A^*(\tau)$ ,  $x, y \in M$ , and all  $k \in (0, 1)$ ,

$$p_{\alpha}(Tx - Ty) \le p_{\alpha}(Ix - Iy) + \frac{1 - k}{k} \max\{d_{p_{\alpha}}(Ix, [q, Tx]), d_{p_{\alpha}}(Iy, [q, Ty])\}, \quad (2.2)$$

then I and T have a common fixed point in M provided one of the following conditions holds:

- (i) M is  $\tau$ -compact and T is continuous.
- (ii) M is weakly compact in  $(E, \tau)$ , I is weakly continuous and I T is demiclosed at 0.

**Proof.** Define  $T_n: M \to M$  by

$$T_n x = (1 - k_n)q + k_n T x$$

for some q and all  $x \in M$  and a fixed sequence of real numbers  $k_n(0 < k_n < 1)$  converging to 1. Then, for each  $n, T_n(M) \subseteq I(M)$  as M is convex, I is linear, Iq = q and  $T(M) \subseteq I(M)$ . Further, since the pair  $\{I, T\}$  is subcompatible and I is linear with Iq = q so, for any  $\{x_m\} \subset M$  with  $\lim_m Ix_m = \lim_m T_nx_m = t \in M$ , we have

$$\lim_{m} p_{\alpha}(T_{n}Ix_{m} - IT_{n}x_{m}) = k_{n} \lim_{m} p_{\alpha}(TIx_{m} - ITx_{m})$$

$$= 0.$$

Thus the pair  $\{I, T_n\}$  is compatible on M for each n. Also, we obtain from (2.2),

$$p_{\alpha}(T_{n}x - T_{n}y) = k_{n}p_{\alpha}(Tx - Ty)$$

$$\leq k_{n}\{p_{\alpha}(Ix - Iy) + \frac{1 - k_{n}}{k_{n}}\max\{p_{\alpha}(Ix - T_{n}x), p_{\alpha}(Iy - T_{n}y)\}\}$$

$$= k_{n}p_{\alpha}(Ix - Iy) + (1 - k_{n})\max\{p_{\alpha}(Ix - T_{n}x), p_{\alpha}(Iy - T_{n}y)\},$$

for each  $x, y \in M$ ,  $p_{\alpha} \in A^*(\tau)$  and  $0 < k_n < 1$ .

(i) M being  $\tau$ -compact is  $\tau$ -bounded and  $\tau$ -complete. Thus by Theorem 2.6, for each  $n \geq 1$ , there exists an  $x_n \in M$  such that  $x_n = Ix_n = T_nx_n$ . Now the  $\tau$ -compactness of M ensures that  $\{x_n\}$  has a convergent subsequence  $\{x_j\}$  which converges to a point  $x_0 \in M$ . Since  $x_j = T_jx_j = k_jTx_j + (1 - k_j)$  and T is continuous, so we have, as  $j \to \infty$ ,  $Tx_0 = x_0$ . The continuity of I implies that

$$Ix_0 = I(\lim_j x_j) = \lim_j I(x_j) = \lim_j x_j = x_0.$$

(ii) Weakly compact sets in  $(E, \tau)$  are  $\tau$ -bounded and  $\tau$ -complete so again by Theorem 2.6,  $T_n$  and I have a common fixed point  $x_n$  in M for each n. The set M is weakly compact so there is a subsequence  $\{x_j\}$  of  $\{x_n\}$  converging weakly to some  $y \in M$ . The map I being weakly continuous gives that Iy = y. Now

$$x_j = I(x_j) = T_j(x_j) = k_j T x_j + (1 - k_j)q$$

implies that  $Ix_j - Tx_j = (1 - k_j)[q - Tx_j] \to 0$  as  $j \to \infty$ . The demiclosedness of I - T at 0 implies that (I - T)(y) = 0. Hence Iy = Ty = y.

An application of Theorem 2.7 establishes the following result in best approximation theory.

**Theorem 2.8.** Let T and I be selfmaps of Hausdorff locally convex space  $(E,\tau)$  and M a subset of E such that  $T(\partial M)\subseteq M$ , where  $\partial M$  denotes boundary of M and  $u\in F(T)\cap F(I)$ . Suppose that  $P_M(u)$  is nonempty convex containing  $q, q\in F(I), I$  is nonexpansive and linear on  $P_M(u)$  and  $I(P_M(u))=P_M(u)$ . If the pair  $\{I,T\}$  is subcompatible on  $P_M(u)$  and satisfies, for all  $x\in P_M(u)\cup \{u\}, p_\alpha\in A^*(\tau)$  and  $k\in (0,1)$ ,

$$p_{\alpha}(Tx - Ty)$$

$$\leq \left\{ \begin{array}{cc} p_{\alpha}(Ix - Iu) & \text{if } y = u, \\ p_{\alpha}(Ix - Iy) + \frac{1-k}{k} \max\{d_{p_{\alpha}}(Ix, [q, Tx]), d_{p_{\alpha}}(Iy, [q, Ty])\}, & \text{if } y \in P_{M}(u), \end{array} \right.$$

then  $P_M(u) \cap F(I) \cap F(T) \neq \emptyset$ , provided one of the following conditions is satisfied:

- (i)  $P_M(u)$  is  $\tau$ -compact and T is continuous on  $P_M(u)$ .
- (ii)  $P_M(u)$  is weakly compact in  $(E, \tau)$ , I is weakly continuous and I T is demiclosed at 0.

**Proof.** Let  $y \in P_M(u)$ . Then as in the proof of Theorem 2.6 of [15](see also [9,12])  $Ty \in P_M(u)$  which implies that T maps  $P_M(u)$  into itself and the conclusion follows from Theorem 2.7.

Remark 2.9. (i) 1-subcommuting maps are subcompatible, consequently, Theorem 2.2-Theorem 3.3 due to Hussain and Khan [7] and Theorem 2.3 of Khan and Hussain [14] are improved and extended.

(ii) Commuting maps are subcompatible so Theorems 2.7-2.8 are proper generalization of the main results of Brosowski [2], Habiniak [6], Sahab et al. [18], Sahney et al. [19], Singh [23,24], Tarafdar [25], Theorems 6-7 due to Jungck and Sessa [13] and Theorem 2.6 due to Khan et al. [15].

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